

SWIR



# SASI-600 v2

Airborne Hyperspectral Solutions.



SWIR Imager  
100 Spectral Channels  
40 degree FOV, 600 Spatial Pixels  
0.95 - 2.45 micron Spectral Range  
Diffraction Limited Optics



# SASI-600 v2

## Sensor Type

SWIR Pushbroom Sensor (Shortwave IR Airborne Spectrographic Imager)

## Performance

<b>Spectral Range (Continuous Coverage)</b>	<b>950-2450 nm</b>
# Spectral Channels	100
# Spatial Pixels	600
Total Field of View	40 degrees
IFOV	1.2 mRad
f/#	f/2
Spectral Width Sampling/Row	15 nm average
Spectral Resolution (FWHM)	15 nm average
Pixel Size	30x30 microns
Dynamic Range	14-bits (16384:1)
Sustained Data Rate - Mega-pixels/Second	3.6 Mpix/sec
Spectral Smile/Keystone Distortion	±0.35 pixels
Peak Signal to Noise Ratio (SNR)	SNR models for various radiance conditions are available from ITRES

## Dimensions, Weights, and Power

Item	Dimensions (cm)	Weight (kg)
SHU	W 44.0 H 86.8 D 20.0	32
ICU (Single)	W 48.3 H 17.8 D 52.3	16
15" Display	W 41.0 H 30.9 D 6.52	8
Power (SHU + ICU)	24-32VDC 25.5A (Typical)	

## Environmental Constraints

<b>Operating Temperature</b>	Ambient 0 to +35°C (+32 to +104°F) RH 20-80% non-condensing
<b>Maximum Altitude</b>	3,048 m (10,000 ft) ASL (unpressurized, non-condensing environment)
<b>Storage Temperature</b>	Optimum -20 to +60°C (-4 to +120°F) RH 10-90% non-condensing

## Operation

<b>Display</b>	15" sunlight readable, 1024x768 resolution.
<b>Operator Control</b>	Via keyboard, Windows™ OS
<b>Real-Time Display</b>	Scene image, diagnostics, signal level display
<b>Remote Diagnostics</b>	Ethernet-ready remote diagnostic capability on ICU
<b>Data Storage</b>	Swappable mass storage

## Data Processing System

- Processing software Linux and Windows-based
- Playback software (Quicklook)
- Generates 16-bit BIP format data compatible with ENVI (BIL, BSQ formats possible)
- ASCII format ancillary QC data output - clocking, attitude, logging, GPS, and sensor health monitoring information
- Outputs diagnostic information
- Selectable band output

## Geocorrection System

- GPS/IMU processing
- Data synchronization (GPS, attitude, and image streams)
- After bundle adjustment no need for GCPs
- Stabilized mount option

## Geocorrection/Orthocorrection Software

- Best nadir pixel selection function during mosaicking
- Accepts Lidar, Ifsar, and USGS DEM inputs
- Nearest neighbor algorithm used - maintains radiometric fidelity
- Separately stores ancillary data (e.g. pointing vector, DEM)

## Spatial Resolution & Flight Altitude

- Across-track spatial resolution depends on flight altitude  
For example, if 1 m pixels are desired, then flight altitude = 824 m AGL
- Along-track pixel dimension depends on frame rate and aircraft speed  
Frame rate fixed for SASI; for 1 m pixels, required flight speed is 120 knots.

